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The challenges of devising next generation automotive benchmarks

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Never stop thinking

Agenda

Automotive System Trends

Market requirements

Benchmark requirements

Workload characterization

New Benchmark

Summary

Key Market Drivers

CO2 Reduction



Pollution Reduction



HC, CO, NOx, PM

Safety



Fun to Drive



Global CO₂ Targets



It's the law: 35 mpg CAFE

Automotive News Dec. 19th 2007

Cars: 35 mpg by 2020



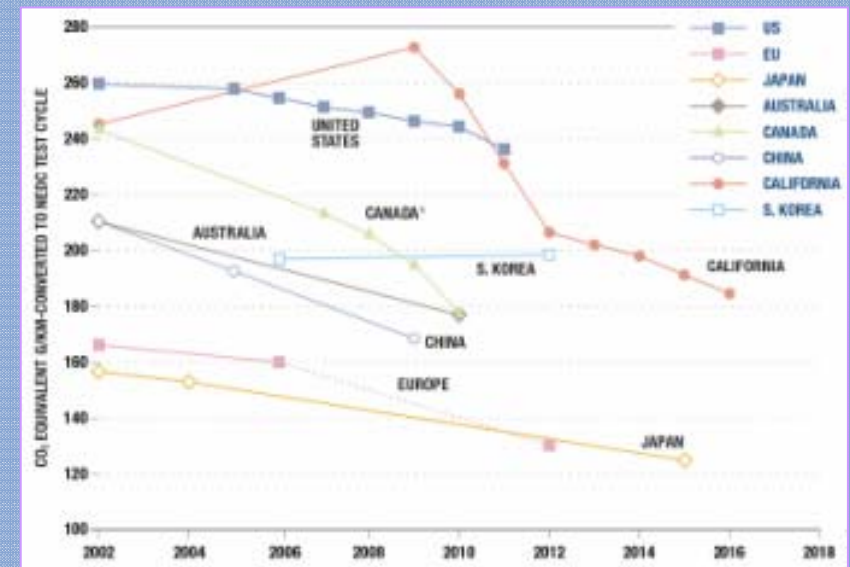
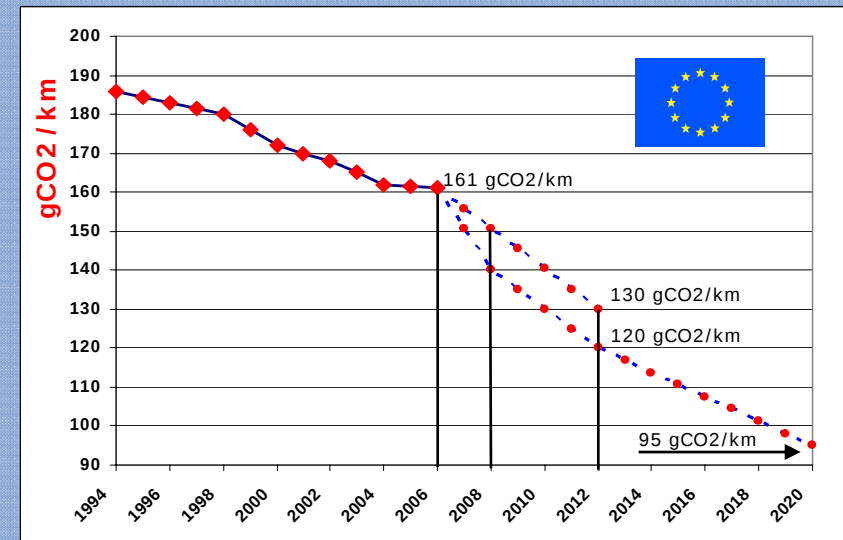
EU agrees to steep fines to cut car CO₂ from 2012

Automotive News Dec. 20th 2007

**Cars: 120gCO₂/km by 2012
+10 g coming from biofuels ...**

Conversion table for regular gasoline engine

gCO ₂ /km	155	140	130	120	110	100	90
L / 100km	6.72	6.08	5.65	5.21	4.78	4.34	3.91
MPG	35.00	38.69	41.66	45.13	49.24	54.16	60.18



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General Architectural Trends and Requirements for Semiconductors

Trend	Application Examples		IC Requirements
Software-enabled functionality	Replacement of dedicated hardware with software algorithms running on μ C		Strong microcontroller cores with RT capabilities, broad peripheral set and eFlash
Decentralization to Centralization	μ C-enabled global controls		High performance processors with network connectivity
Centralization to Decentralization	Smart sensor networks, dedicated board nets		Broad IP portfolio (sensors, μ C, power) HVCMOS and advanced packaging technology
Analog/Digital Tradeoff	Replacement of signal processing and communication from analog to digital		A/D and D/A conversion, signal conditioning and processing
X-by-Wire	Mechatrical solutions for steering, braking instead of mechanical systems		RT capabilities, failsafe electronics

Software-Enabled Functionality

Increased Microcontroller Performance

Semiconductor Industry provides a 30 % to 60 % annual performance increase at same cost

Software platform, reuse of software modules across application and customers

Migration of functions from hardware to software

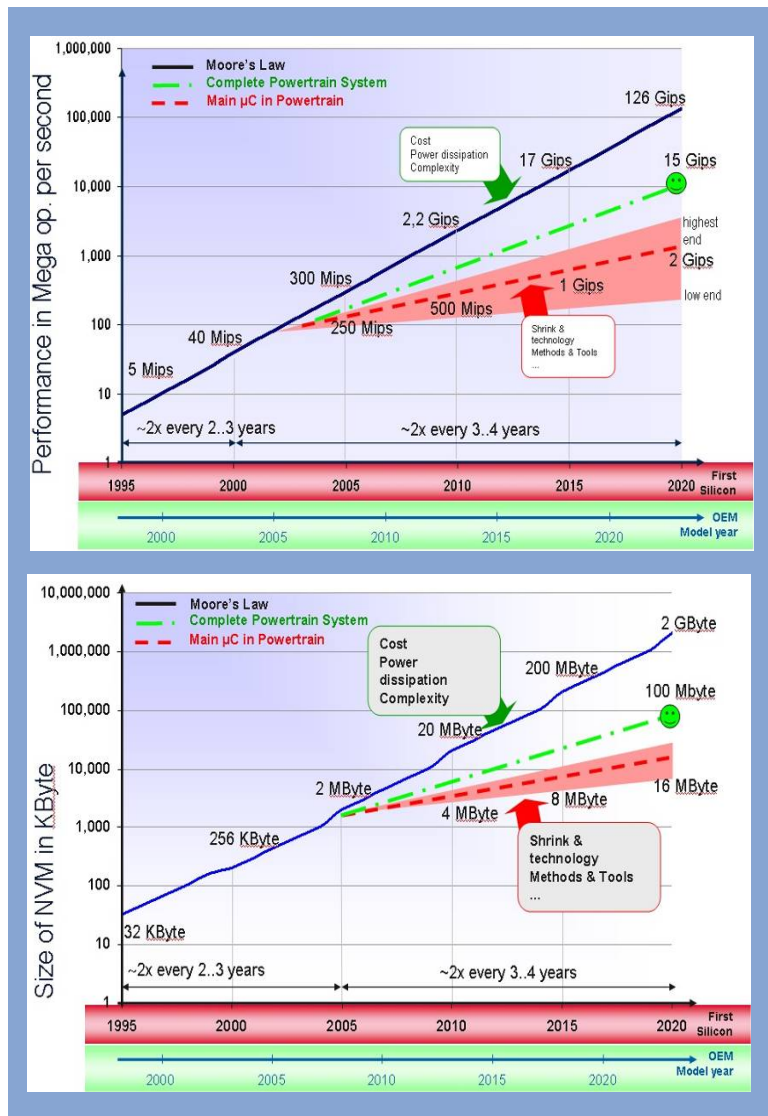
Hardware independent Software

Wider use of automatic code generation

Software standardization e.g. Operating system, Drivers with application level interfaces (OSEK, AutoSar, IEC61508, ISO26262...)

Robust, transparent software e.g. encapsulation, software self test

µC family concept with performance increase and easy migration path



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Benchmarks that Predict Performance in Real-world Applications

Not MHz

- ⌘ Only provides relative performance analysis

Not Dhrystone

- ⌘ No regulation
- ⌘ No memory or cache effects
- ⌘ Optimizes to nothing

Usage Models

- ⌘ Is a substitute of the real application to model the system performance and memory size utilization
- ⌘ Analyze, tune, and validate new processor architectures
- ⌘ Design and analysis of system-level implementation
- ⌘ Compare and select processors according to more important criteria than MHz

Vision of the benchmark

The vision is to establish this new benchmark as an automotive tool to specify and measure performance between:

1. OEMs
2. Tier1s
3. Silicon vendors
4. 3rd party tool vendors

The relevance of the benchmark

The automotive is more going toward the system benchmark

1. Static Benchmark
 - Test of given algorithm
2. Dynamic Benchmark
 - Test of response, switch context...
3. Functional Benchmark
 - Test of complete function CAN, LIN, PWM, ADC
4. Auto code Benchmark

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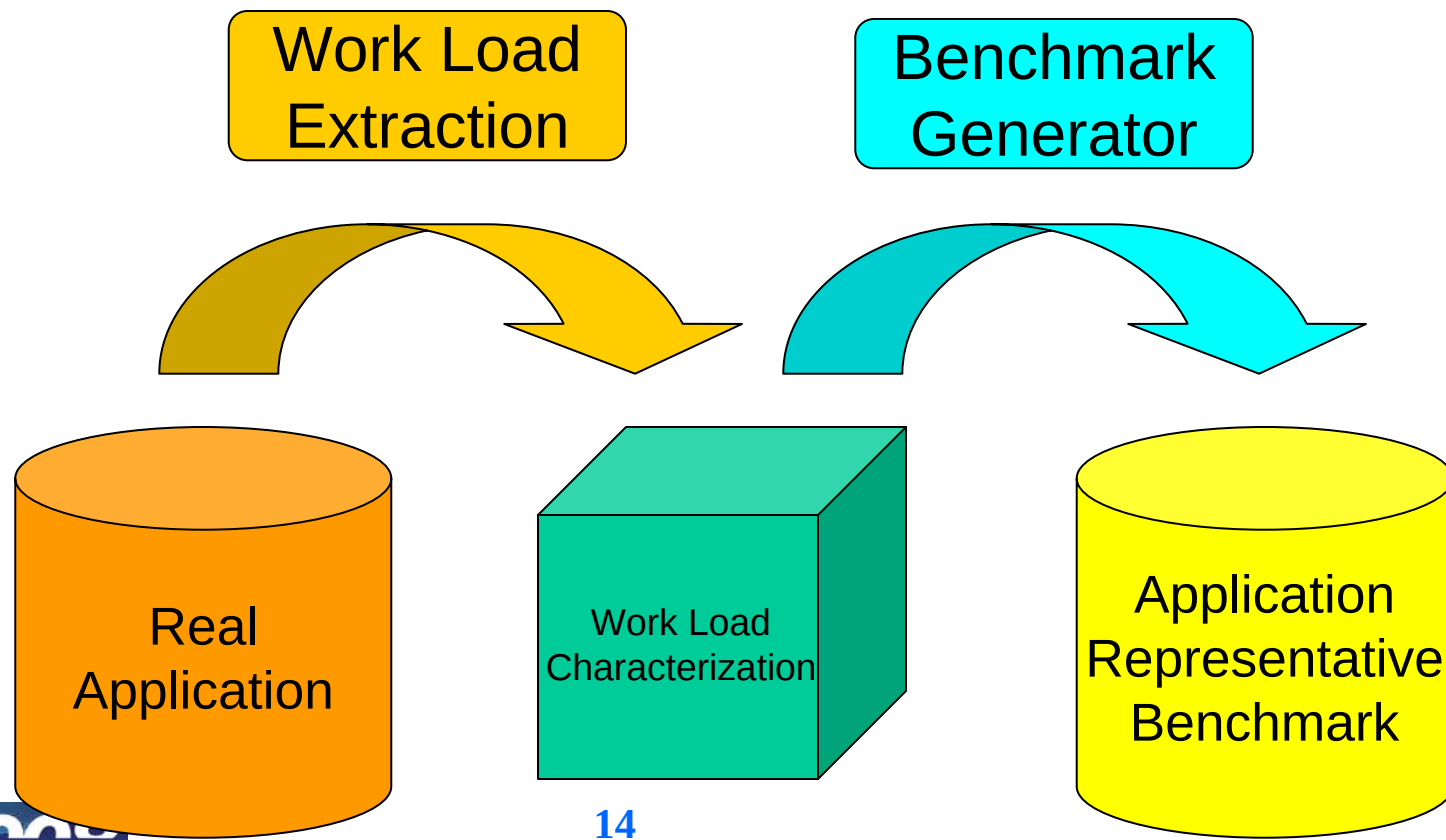
New Benchmark

Summary

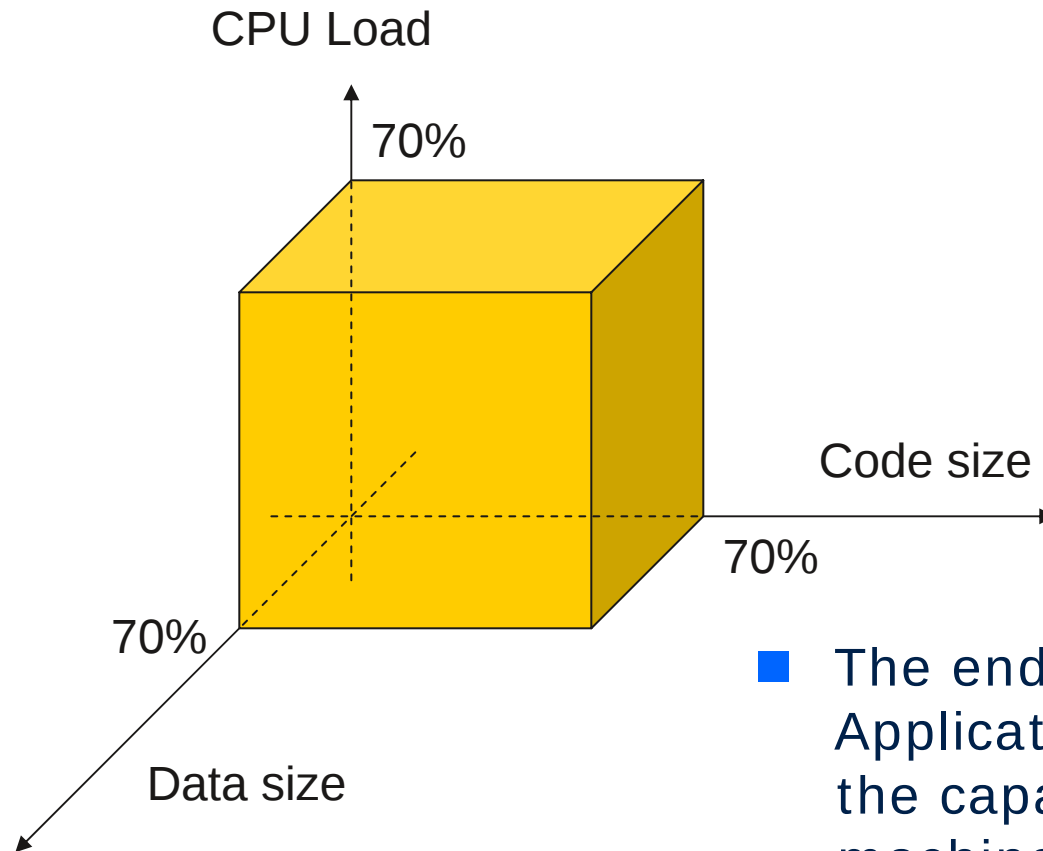
Proposal EEMBC Automotive Suite V2

- Two big needs

1. Work load extraction
2. Application Representative Benchmark generator



Application Characterization

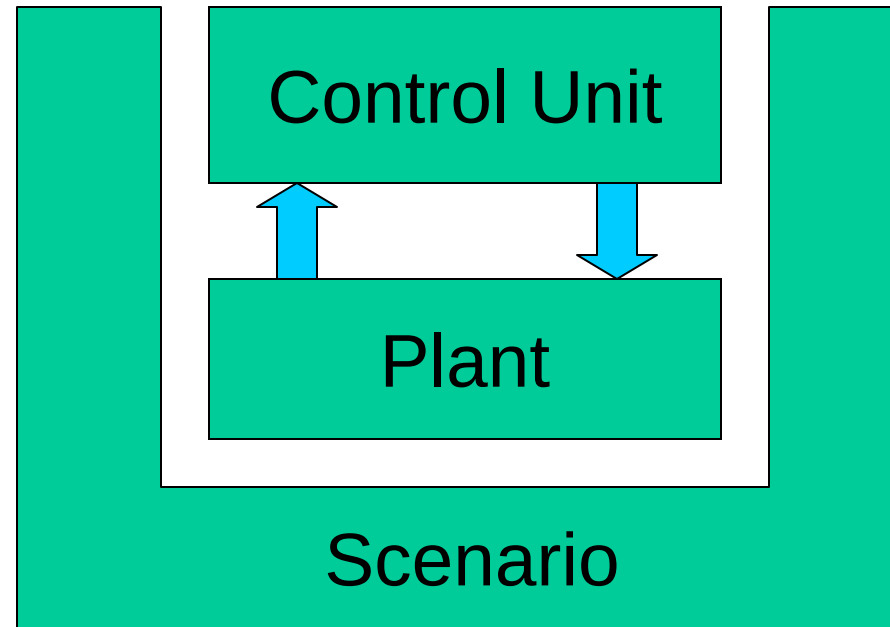


- The end customers like the Application to be at 70% of the capability of the machine at the first SOP of the product / platform

Embedded Software

To assess performance of a μ C for an application is important to have a good knowledge of:

1. Control Algorithm
2. Plant Algorithm
3. Scenario



Work load characterization

At Source Code level

1. This analyses the source code
2. Without care of the use cases

At Trace code level

1. This analyses a given code trace
2. For a give plant and a given scenario
3. E.g. Full load, Idle, Engine Acceleration..

Benchmark Characterization

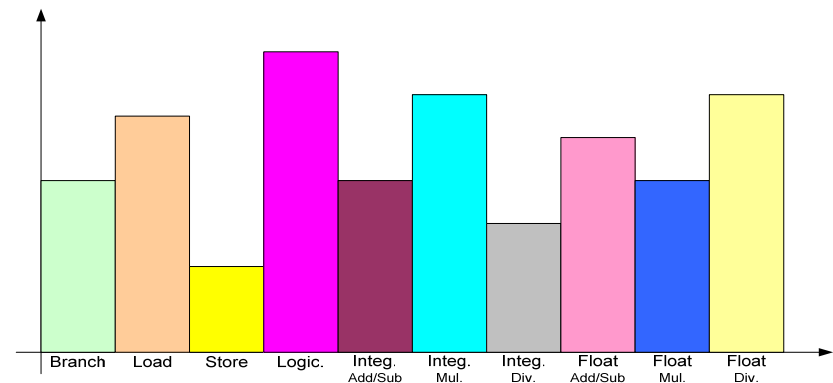
Multiple parameters:

1. Instruction distribution
2. Inherent instruction-level parallelism (ILP)
3. Branch predictability
4. Inherent floating-point (FU) usage
5. Minimum cache size to minimize misses



Instruction distribution at Application level

At Source Code level

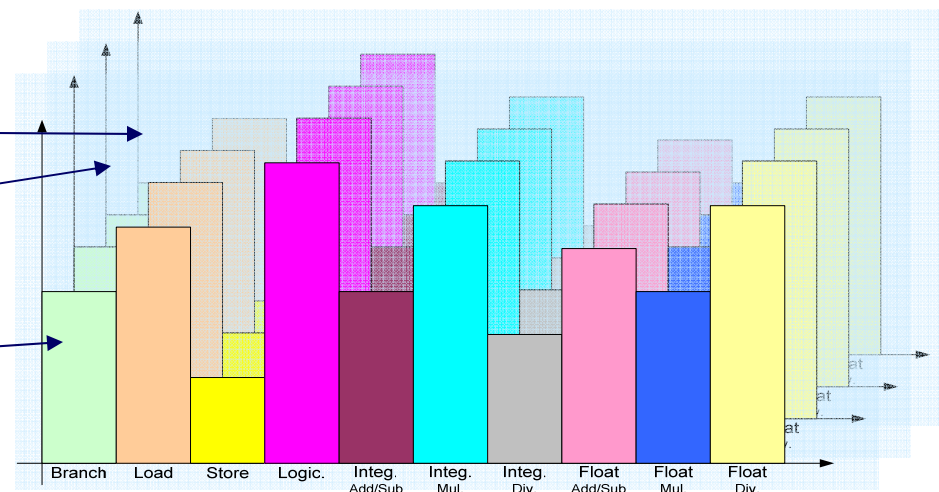


At Trace Code level

Trace 1

Trace 2

Trace n



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Algorithm selection

Arithmetic Fundamentals

Bit manipulation
Basic Calculation, Saturation & Rounding
Polynomial equations and limited dev.
Table look-up & Interpolation
Zeros of a 2nd order equation
Trigonometric
Logarithmic, Exponential, X Power Y
Vector and Matrix functions

Control

Finite state machine
PID
Kalman + LQG

Filters

De-bounces
Schmidt trigger
Finite Impulse Response (FIR) Filter
Infinite Impulse Response (IIR) Filter
Fast Fourier Transform (FFT)
Inverse Fast Fourier Transform (iFFT)
Discrete Cosine Transform (DCT)
Inverse Discrete Cosine Transform (iDCT)

Statistics

Autocorrelation
Convolution
Mean Value, Variance, Standard deviation
Linear regression
Random sequence

Instruction distribution

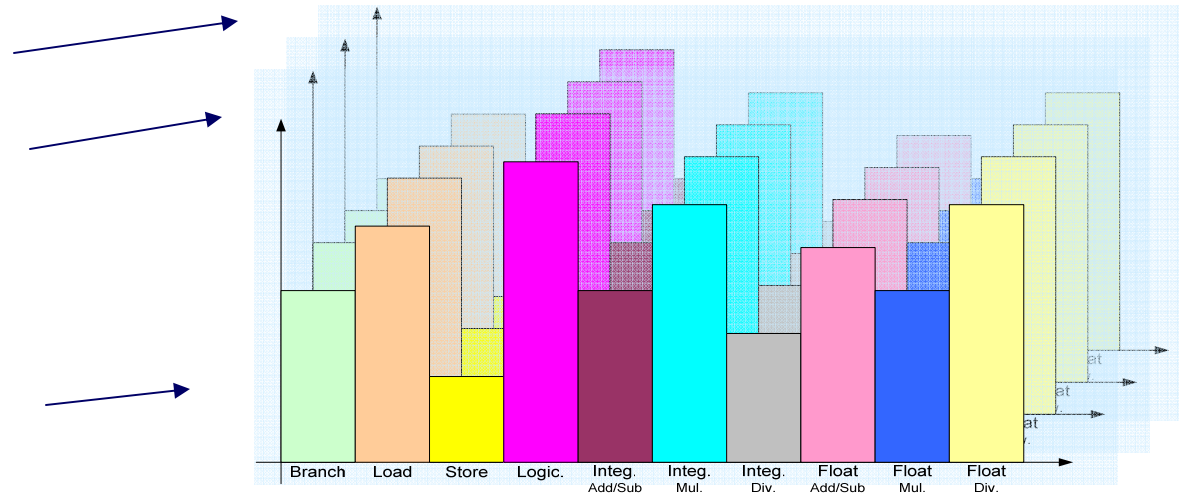
At Reference Algorithm level

Ref. Algorithm 1

Ref. Algorithm 2

Ref. Algorithm 3

Ref. Algorithm n

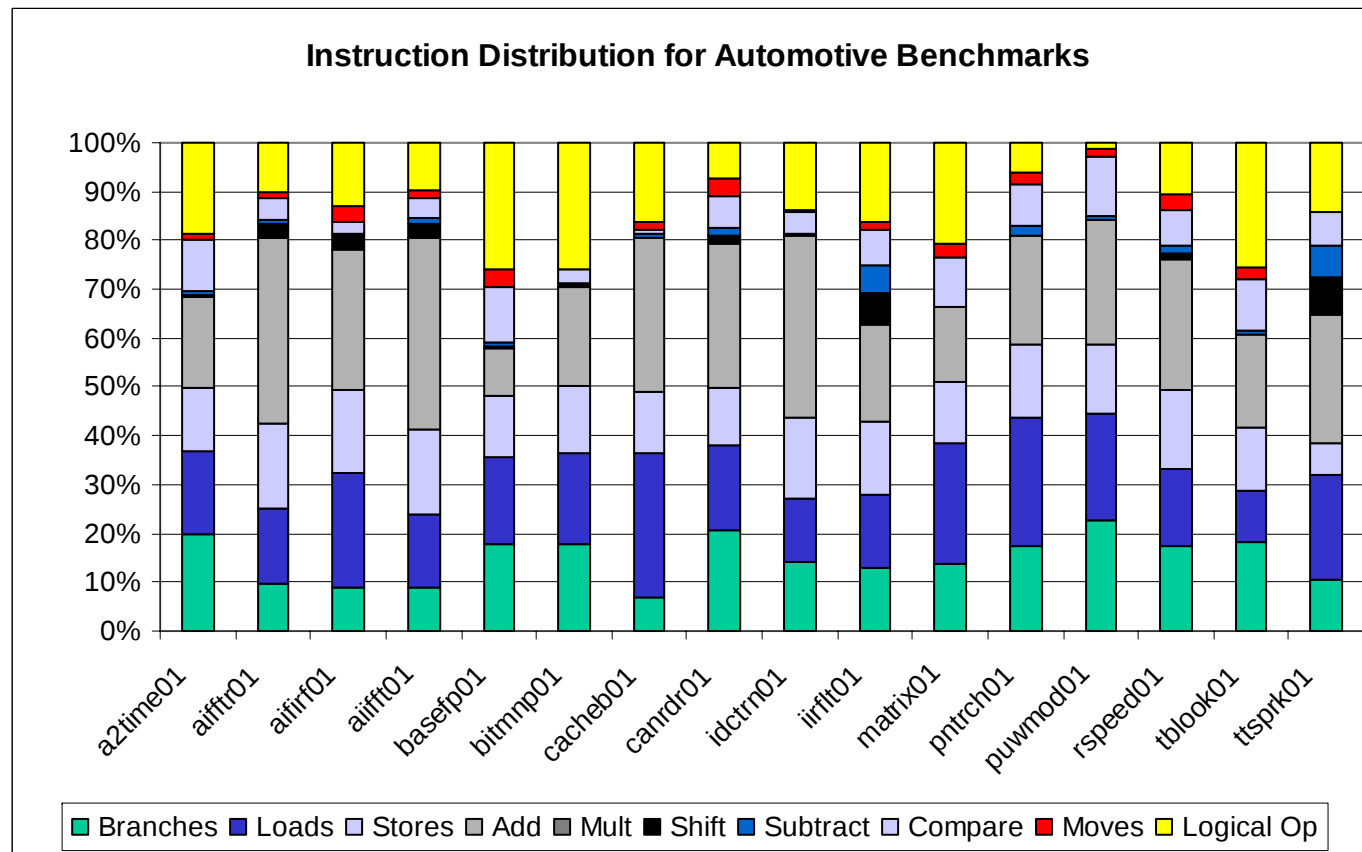


Level of definition

Algorithm parameters (Format, dimension..)

Algorithm data set

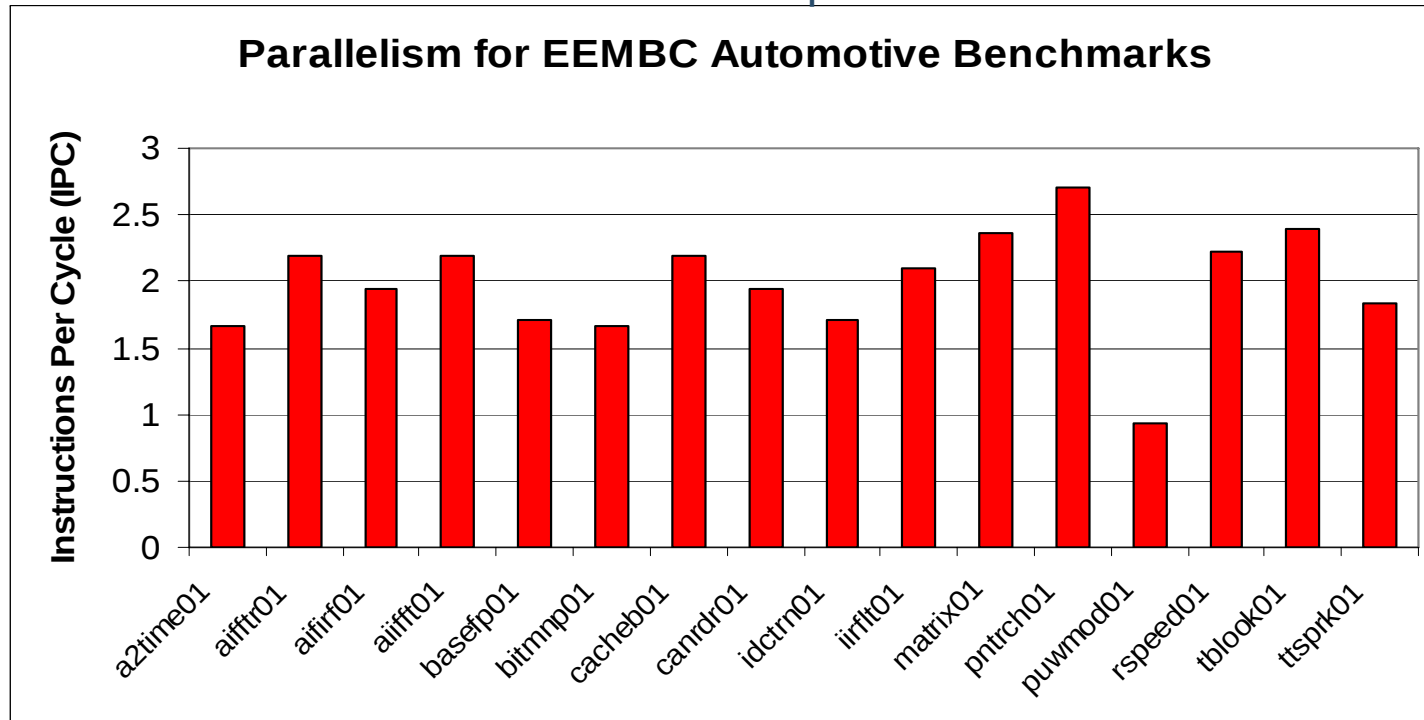
Instruction distribution



EEMBC Automotive V1

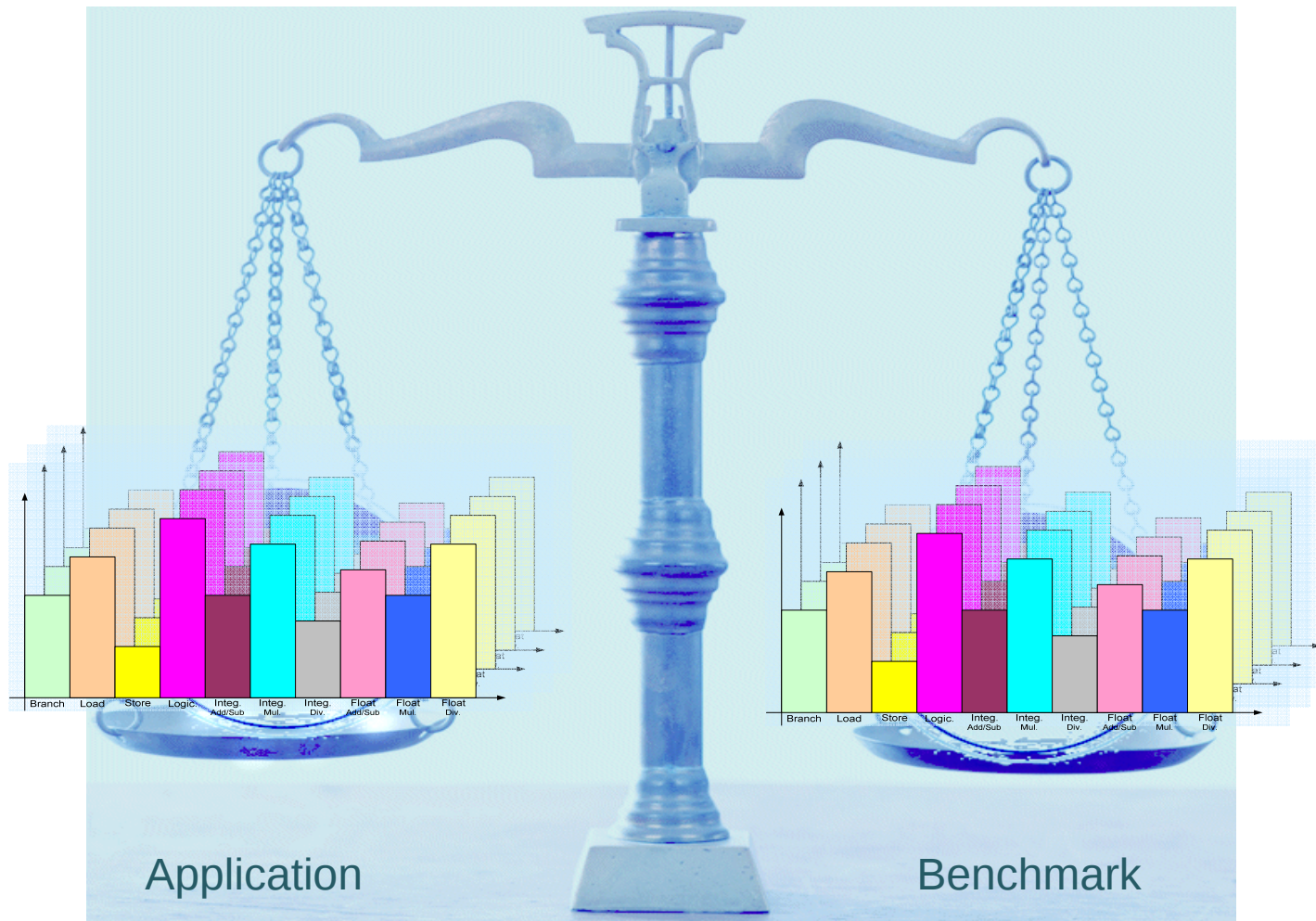
Inherent ILP

Inherent instruction-level parallelism



EEMBC Automotive V1

Benchmark Fitting / Tuning

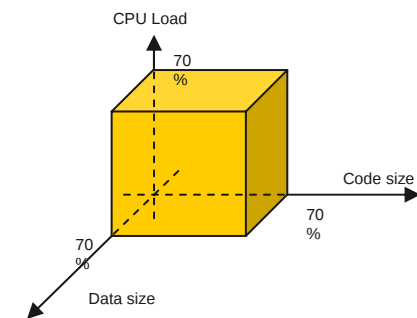
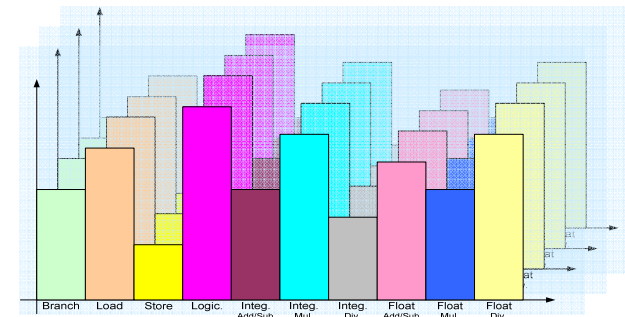


Benchmark Fitting / Tuning

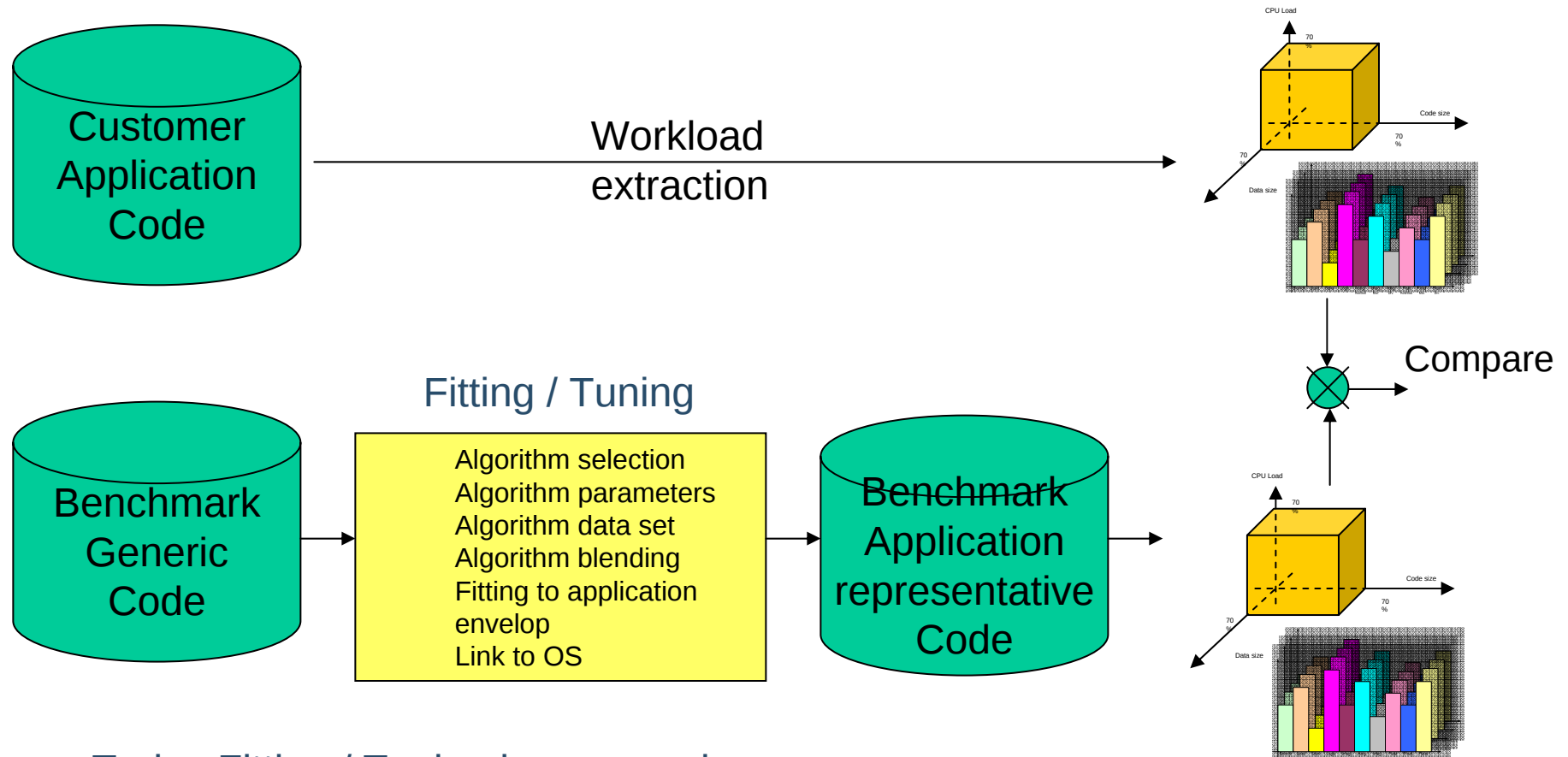
Customer Code

Benchmark Code

- ≡ Algorithm selection
- ≡ Algorithm parameters
- ≡ Algorithm data set
- ≡ Algorithm blending
- ≡ Fitting to application envelop
- ≡ Link to OS

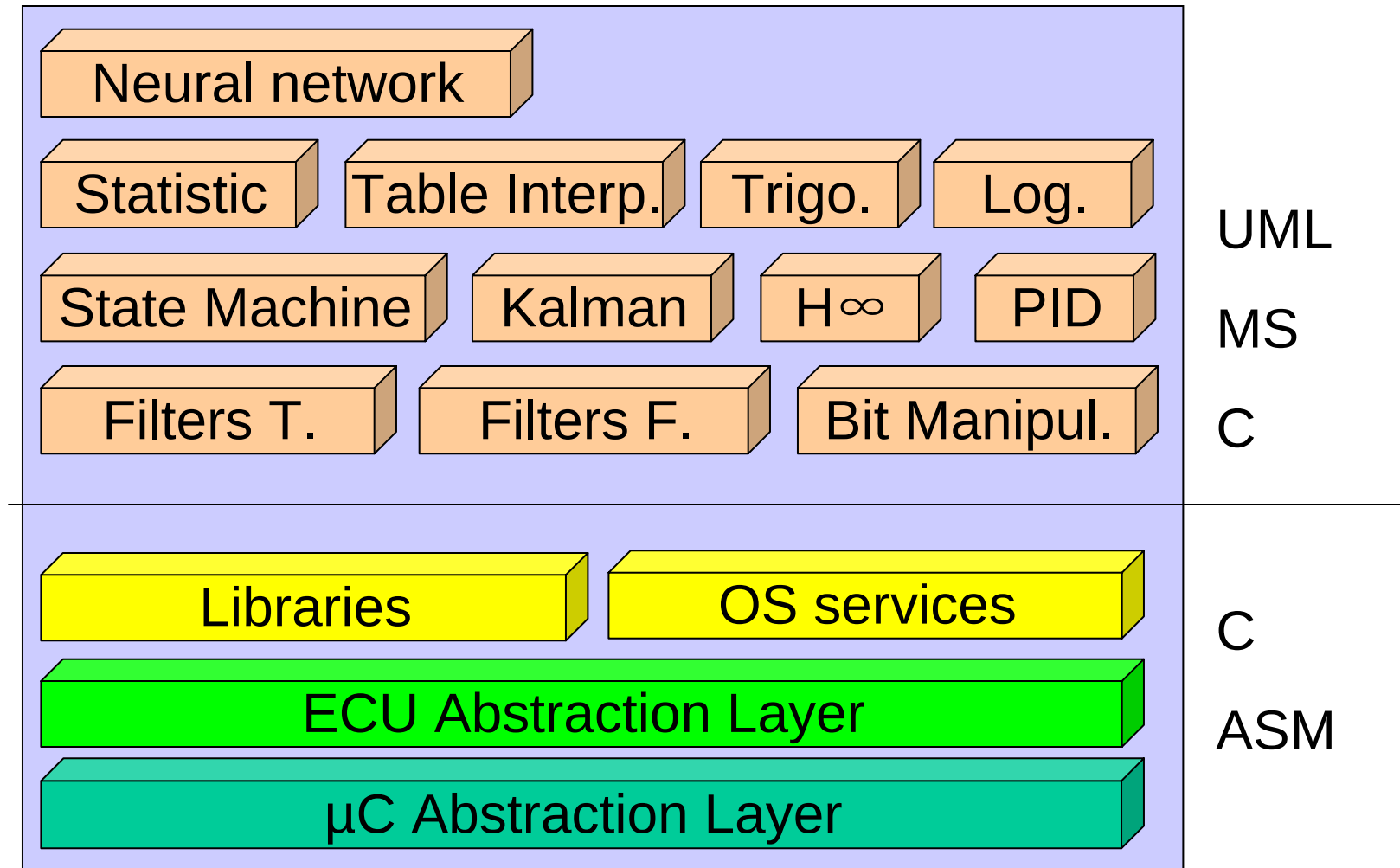


Benchmark Fitting / Tuning



Today Fitting / Tuning is a manual process
in the future this could be semi-automatic or fully-automatic

Software architecture (Static view)



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Summary

- It is possible to create a benchmark to substitute the application code and be representative.
- This benchmark is a tool share performance information between OEMs, Tier1s, Silicon vendors, SW vendors and Tool suppliers...
- This benchmark is a tool to better architect HW and SW for next generation Automotive Electronics.



Acknowledgement

EEMBC: The Embedded Microcontroller Benchmark Consortium

<http://www.eembc.org>

Markus Levy
EEMBC President

Shay Gal-On
EEMBC Director of Software Engineering

The challenges of devising next generation automotive benchmarks

Thank you for your attention

Q&A